Parameter	Inhalt
Dateiname:	0003Papa.jsn
Pfad:	C:\Users\hermann\Dropbox\Modellflug\jeti\jeti dc16\
Modellname:	**Papagei**
Modellzeit:	16:30
gebundener Empfänger:	42641:32384
Modelltyp:	Flächenmodell
Flügeltyp:	2 QR
Leitwerkstyp:	Kreuz- oder T-LW 1 HR 1 SR
Motor Aus Schalter	SD,unten
Leerlaufschalter	nicht zugewiesen
Autotrimm Schalter	nicht zugewiesen
Trainer Schalter	SA,unten
Logging Schalter	nicht zugewiesen
Telemetrie Ansage Schalter	nicht zugewiesen

Flugphasen	Schalter, Stellung	ID	Label	Audio	Delay	Switch	DigiTrim	Value	Stored	Step	Max-Pos	Max-Neg	Mode	Group	FuncID
>		1	Standard		0	0,0,0,0,1,4000,-1,0		-6	0	2	100	100	0	0	1

Funktionen	Geber / Schalter	ID	Label	Control	Trim-Control	Trim-Max	Trainer-Enabled	Trainer-Value	Trainer-Channel	G-Trim	G-Curve	G-DR
>	Geber P1	1	Quer	1,0,1,1,1,0,-1,1	0,0,1,1,1,4000,-1,0	50	0	100	1	1	1	1
>	Geber P2	2	Höhe	2,0,1,1,1,0,-1,1	0,0,1,1,1,4000,-1,0	50	0	100	2	1	1	1
>	Geber P3	3	Seite	4,0,1,1,1,0,-1,1	0,0,1,1,1,4000,-1,0	50	0	100	3	1	1	1
>	Geber P4	4	Drossel	3,0,1,1,1,0,-1,1	0,0,1,1,1,4000,-1,0	50	0	100	4	1	1	1
>	Geber P5	14	P5	5,0,1,1,1,4000,-1,7	0,0,1,1,1,4000,-1,0	50	0	100	5	1	1	1
>	Geber P6	15	P6	6,0,1,1,1,4000,-1,7	0,0,1,1,1,4000,-1,0	50	0	100	6	1	1	1

Funktionsspezifikationen	Flugphase, Funktion, DR-Schalter	Flight-Mode	Function-Id	FM-Delay	Ph-Trim	Expo-Pos	Expo-Neg	DR-Pos	DR-Neg	Delay-Pos	Delay-Neg	Sym	DR-Switch	Curve-Type	Points-In	Points-Out
>	Standard: Quer	0	1	1	0,0,0,0	0,0,0	0,0,0	100,100,100	100,100,100	0	0	1	0,0,0,1,1,4000,-1,0	0	0	0
>	Standard: Höhe, DR-S: SH,unten	0	2	1	0,0,0,0	0,0,0	0,0,0	60,100,100	60,100,100	0	0	1	16,0,0,1,1,-4000,-1,1	0	0	0
>	Standard: Seite	0	3	1	0,0,0,0	50,0,0	50,0,0	100,100,100	100,100,100	0	0	1	0,0,0,1,1,0,-1,0	0	0	0
>	Standard: Drossel	0	4	0	0,0,0,0	0,0,0	0,0,0	100,100,100	100,100,100	0	0	1	0,0,0,1,1,4000,-1,0	0	0	0
>	Standard: P5	0	14	1	0,0,0,0	0,0,0	0,0,0	100,100,100	100,100,100	0	0	1	0,0,0,1,1,4000,-1,0	0	0	0
>	Standard: P6	0	15	1	0,0,0,0	0,0,0	0,0,0	100,100,100	100,100,100	0	0	1	0,0,0,1,1,4000,-1,0	0	0	0

Servoeinstellungen	Rx-Kanal, Laufrichtung, Mittenstellung	Index	Servo-Code	Middle	Max-Positive	Max-Negative	Max-Positive-Limit	Max-Negative-Limit	Fail-Safe-Pos	Delay-Positive	Delay-Negative	Offset	Servo-Reverse	Curve		
>	Rx K1, Laufr. normal, Mitte=0%	1	271	0	100	-100	100	-100	0	0	0	0	0	0,0,0,0,0,0,0,0,0,0,0,0		
>	Rx K2, Laufr. normal, Mitte=-5%	2	257	-5	100	-100	100	-81	0	0	0	0	0	0,0,0,0,0,0,0,0,0,0,0,0		
>	Rx K3, Laufr. reverse, Mitte=0%	3	267	0	100	-65	100	-105	0	0	0	0	1	0,0,0,0,0,0,0,0,0,0,0,0		
>	Rx K4, Laufr. normal, Mitte=16%	4	265	16	90	-85	110	-85	0	0	0	0	0	0,0,0,0,0,0,0,0,0,0,0,0		
>	Rx K5, Laufr. normal, Mitte=0%	5	258	0	100	-100	79	-100	0	0	0	0	0	0,0,0,0,0,0,0,0,0,0,0,0		
>	Rx K6, Laufr. normal, Mitte=0%	6	288	0	100	-100	125	-125	0	0	0	0	0	0,0,0,0,0,0,0,0,0,0,0,0		
>	Rx K7, Laufr. reverse, Mitte=0%	7	289	0	100	-100	125	-125	0	0	0	0	1	0,0,0,0,0,0,0,0,0,0,0,0		

Timer	von Zeit -> bis Zeit, Schalter	Label	ID	Init-Time	Dest-Time	Tim-Type	Report-Type	Switch	Sw-Rst	Reset-Type	All-Modes	Time	Round-Len	Round-Val
>	00:08:00->00:00:00, nicht zugewiesen	Count Down	1	480000	0	0	3	0,0,0,0,1,0,-1,0	0,0,0,0,1,4000,-1,0	0	0	480000	-1	
>	L1	Motor	2	0	0	0	0	0,0,0,0,1,0,0,0	0,0,0,0,1,4000,-1,0	0	0	0	-1	
>	L1	Segel	3	0	0	0	0	0,1,0,0,1,0,0,0	0,0,0,0,1,4000,-1,0	0	0	0	-1	
>	nicht zugewiesen	akt.Flug	4	0	0	0	0	0,0,0,0,1,4000,-1,0	0,0,0,0,1,4000,-1,0	0	0	0	-1	

Alarme	Schalter, Schalterstellung, Wert	Type	Active	Switch	Var-Greater	Decimals	File	Sensor-ID	Sensor-Param	Repeat	Voice	Thro-Idle	Value
>	Wert:<=4,4	Alarm	1	0,0,0,0,1,4000,-1,0	0	2	NIEDRRXS.WAV	0	1	1	1	0	440
>	Wert:>=2200	Alarm	1	0,0,0,0,1,4000,-1,0	1	0	AKKUKAPA.WAV	1343662177	3	0	1	0	2200
>	Wert:<=10	Alarm	0	0,0,0,0,1,4000,-1,0	0	1	NIEDRIAK.WAV	1343662177	1	2	0	0	100

Logische Schalter	G/S1,Stellung Verkn. G/S2, Stellung	Index	Enabled	Label	Switch1	Switch2	Cond1	Cond2	Value1	Value2	Log-Type
>	L1:Geber P4>-93% UND SD,oben	1	1	Motor ein	3,0,1,1,1,0,-1,1	12,0,0,1,1,4000,-1,3	1	0	-3720	0	1
>	L2:SE,oben ODER MX1,oben	2	1	Tel.Ansage	13,0,0,1,1,4000,-1,4	0,0,0,1,1,4000,48,0	1	0	0	0	2
>	L3:L2,oben ODER MX2,oben	3	1	Kapa	0,0,0,1,1,4000,1,0	0,0,0,1,1,4000,49,0	1	0	0	0	2

Ereignis Ansagen	Geber/Schalter, Stellung	Switch	Delay	Repeat	File
>	SD,oben	12,0,0,0,1,4000,-1,3	0	0	P_ZUEN~1.WAV
>	SD,unten	12,0,0,0,1,-4000,-1,3	0	0	P_ZUEN~2.WAV

Freie Mixer	von Geber > auf Geber	Data
>	Drossel->Seite	4,3,1,0
>	Drossel->Höhe	4,2,1,1
>	P6->Quer	15,1,1,1
>	P6->Höhe	15,2,1,1

Freie Mixer Einstellungen	von Geber > auf Geber, Schalter	Flight-Mode	Intensity	DelayP	DelayN	DelaySwP	DelaySwN	Switch	S-Output	S-OutputN	Direction	M-Link	S-Link	M-Trim	S-DR	S-Diff	Curve-Type	Points-In	Points-Out
>	Standard: Drossel->Seite, 11%	0	11	0	0	0	0	0,0,0,1,1,4000,-1,0	100,100,100,100	100,100,100,100	1	0	0	0	0	1	0	0	0
>	Standard: Drossel->Höhe, 8%	0	8	5	5	0	0	0,0,0,1,1,4000,-1,0	100,100,100,100	100,100,100,100	1	0	0	0	0	1	8	-100,0,100	-100,0,100
>	Standard: P6->Quer, 75%SG	0	75	0	0	0	0	15,0,0,1,1,0,-1,4	100,100,100,100	100,100,100,100	1	0	0	0	0	1	8	-100,0,100	-100,-50,0
>	Standard: P6->Höhe, -8%SG	0	-8	0	0	0	0	15,0,0,1,1,0,-1,4	100,100,100,100	100,100,100,100	1	0	0	0	0	1	8	-100,0,100	-98,-50,1

Telemetrie Geber		Index	Enabled	Label	Sensor-ID	Param	Decimals	Default	Switch	Prop	Bin-Data
>	MX1, Akkustand=2000+/-6	1	1	Akkustand	1343662177	3	0	0	0,0,0,0,1,0,-1,0	0	2,5,2000,6
>	MX2, Akkualarm>2250+/-0	2	1	Akkualarm	1343662177	3	0	0	0,0,0,0,1,4000,-1,0	0	1,0,2250,0